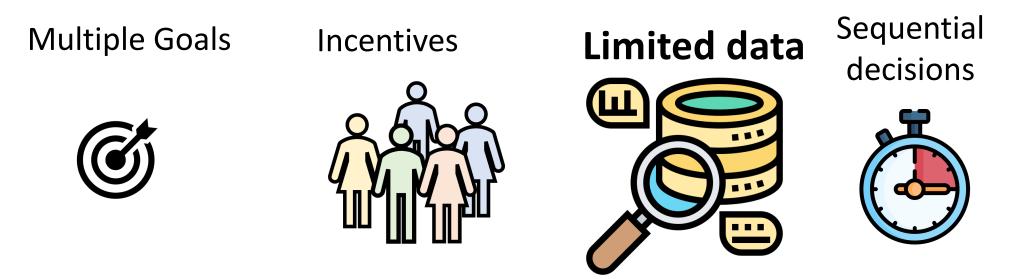
# **Prophet Inequalities**

**Jose Correa** Universidad de Chile

### Motivation

#### Online platforms, e-commerce, etc

Flexible Model:



### **Course Overview**

#### 1. Classic single-choice problems:

The classic prophet inequality, secretary problem, prophet secretary problem, etc

#### 2. Data-driven prophet inequalities:

How can limited amount of data be nearly as useful as full distributional knowledge

#### 3. Combinatorial Prophet Inequalities

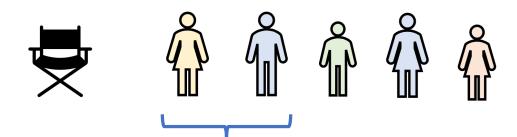
Many ideas for single choice problems, extend to combinatorial contexts such as kchoice, Matching, hyper graph matching, and beyond

#### 4. Online Combinatorial Auctions

General Model that encompasses many online selection/allocation problems

2. Data-driven prophet inequalities

### Secretary Problem



Candidates come in random order

No values, only pairwise comparisons (there is a total order)

Decide STOP/CONTINUE

We maximize  $\mathbb{P}($ select the best)

Optimal algorithm [Dynkin '63][Ferguson '89]

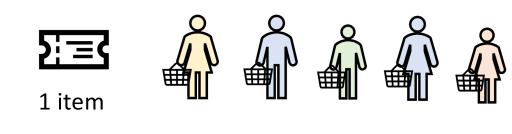
Skip  $\frac{1}{e} \approx 0.367$  fraction of candidates Then, STOP if best so far

Succeeds w.p. 1/e

Optimal guarantee and algorithm are the same if

Candidates have i.i.d. values and we maximize E(selected candidate) (v.s. E(best)) [C., Dütting, Fischer, Schewior, EC'19]

### **Prophet Inequality**

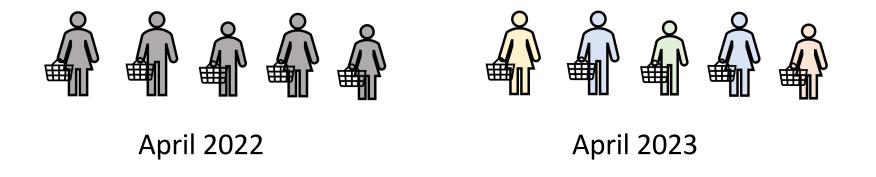


Optimal guarantee: 1/2 [Krengel & Sucheston '77]

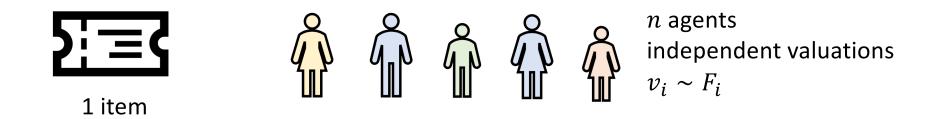
Set a threshold (a price)  $T = \frac{1}{2} \mathbb{E} \left( \max_{i} v_{i} \right)$ [Kleinberg, Weinberg STOC'12] If valuations are i.i.d.

Optimal guarantee is ≈ 0.745 [C., Foncea, Hoeksma, Oosterwijk, Vredeveld EC 2017] Decreasing sequence of thresholds We are given distributions  $F_1, ..., F_n$ Agents arrive one by one At step i: observe  $v_i \sim F_i$  (indep.) and decide STOP/CONTINUE We maximize  $\mathbb{E}(v_{stop})$  and compare with  $\mathbb{E}(\max_i v_i)$ 

Optimal guarantee is 1/e [Allaart & Islas '16] i.i.d. case: ≈ 0. 5801 [Gilbert & Mosteller '66] Random order: ≈ 0.5801 [Nuti, IPCO'22]



# The prophet inequality



- We are given  $F_1, \dots, F_n$ -We are given samples from  $F_1, \dots, F_n$
- Agents arrive sequentially: we observe  $v_1 \sim F_1$ ,  $v_2 \sim F_2$ , ... one by one
- We (the Decision Maker) decide stop/continue
- We maximize  $\mathbb{E}(v_{ ext{stop}})$
- Compare against a prophet that can see realizations in advance and thus gets the optimal social welfare  $\mathbb{E}\left(\max_{i} v_{i}\right)$

# The prophet inequality



1 item

• With full distributional knowledge we know that  $\mathbb{E}(v_{\text{stop}}) \ge \frac{1}{2} \mathbb{E}(\max_{i} v_{i})$ 

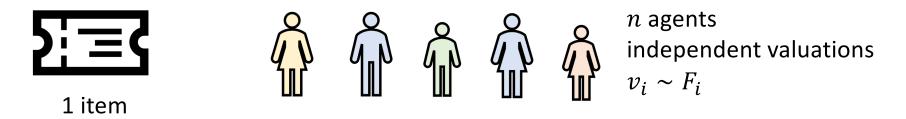
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*n* agents

independent valuations  $v_i \sim F_i$ 

- What if we are only given one sample  $s_1, \ldots, s_n$  from each  $F_1, \ldots, F_n$ ?
- First simple observation: Set  $T = \max\{s_1, ..., s_n\}$ , scan the  $v_i$ 's and stop with first value above T. [Azar, Kleinberg, Weinberg SODA 2014]
- $\mathbb{P}$  (max all 2n values is on the  $v_i$ 's and the second max is on the  $s_i$ 's )  $\geq \frac{1}{4}$
- Then  $\mathbb{E}(v_{\text{stop}}) \ge \frac{1}{4} \mathbb{E}(\max_{i} v_{i})$  Can we do better?

# The prophet inequality



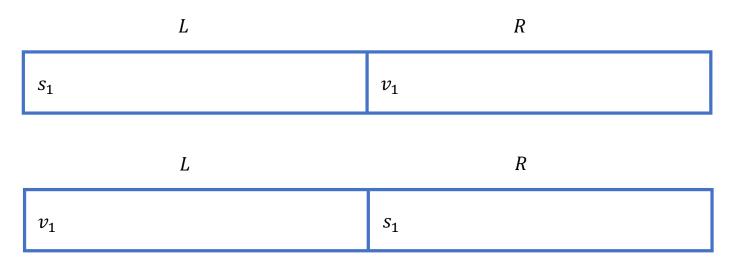
• YES! Algorithm is actually ½ competitive [Rubinstein, Wang, Weinberg ITCS 2020]

Amazing! One sample is enough to get the optimal prophet inequality.

• And this gives yet another Algorithm: Take a random threshold T distributed as the max{ $v_1, ..., v_n$ } so  $F_T = \prod F_i$ 

### Proof

- Take *n* pairs of arbitrary nonnegative numbers, say  $(s_1, v_1), \dots, (s_n, v_n)$
- Call the ordered sequence  $a_1 \ge a_2 \ge \cdots \ge a_{2n}$ .
- Randomly shuffle each pair assigning each element to L and R w.p.  $\frac{1}{2}$



Proof
$$L \qquad R$$

$$s_1 v_2 v_3 s_4 \cdots \qquad v_1 s_2 s_3 v_4 \cdots$$

- Call the ordered sequence  $a_1 \ge a_2 \ge \cdots \ge a_{2n}$ .
- Run ALG on the resulting instance:  $T = \max$  value in L. Stop whenever a value in R surpasses T. Actually take the weaker algorithm that if  $T = a_i$  then it gets  $a_{i-1}$  (except that, if  $T = a_1$ , it gets 0)

$$\mathbb{P}(OPT = a_i) = \mathbb{P}(\max \inf R = a_i) \approx \frac{1}{2^{i-1}} \times \frac{1}{2}$$

$$\mathbb{P}(ALG = a_i) = \mathbb{P}(T = a_{i+1}) \approx \frac{1}{2^i} \times \frac{1}{2} = \frac{1}{2} \mathbb{P}(OPT = a_i)$$

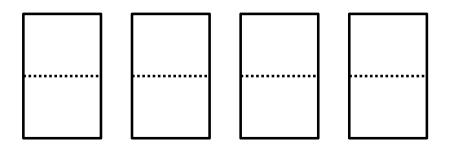
## Prophet Secretary: The two-sided googol

- The secretary problem is also known as the game of googol.
- An adversary writes arbitrary numbers on *n* cards and shuffles them.
- The DM flips the cards one by one and has to stop with the max.



## The two-sided game of Googol

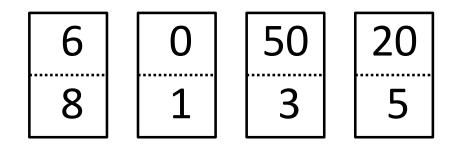
*n* cards with two sides



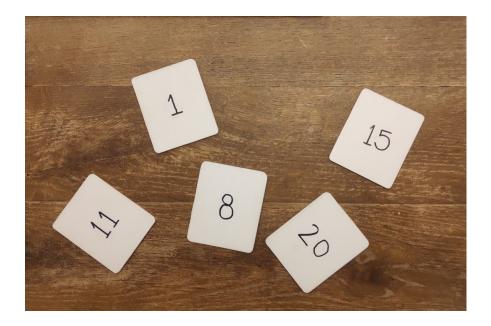
## The two-sided game of Googol

*n* cards with two sides

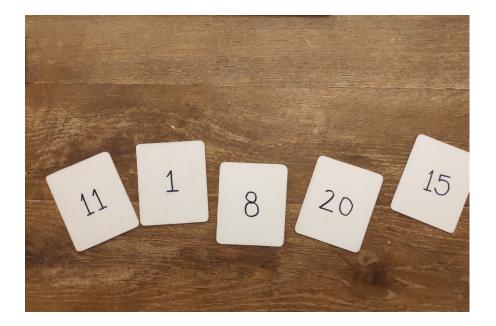
Adversary writes numbers on each side (2*n* in total)



### Playing the two-sided game of Googol Random side revealed

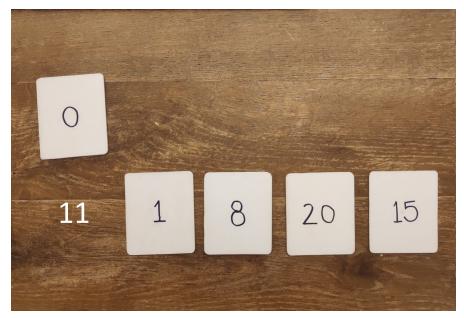


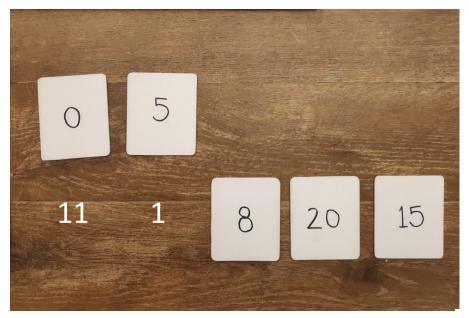
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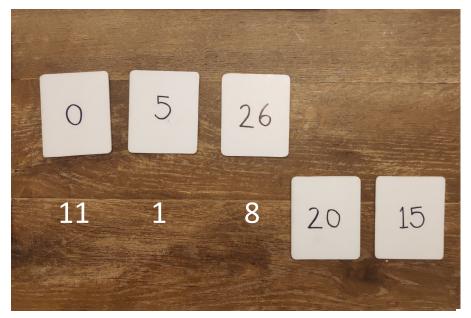


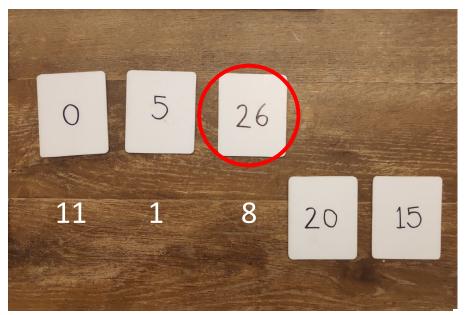
### Playing the two-sided game of Googol Random side revealed











Objective: Maximize expectation of accepted value Benchmark: Expectation of largest hidden value

### Main results

**Theorem.** There is a stopping rule  $ALG^*$  for the two-sided game of Googol such that

 $\mathbb{E}(ALG^*) \geq 0.635 \cdot \mathbb{E}(OPT)$ [C., Cristi, Epstein, Soto SODA 2020]

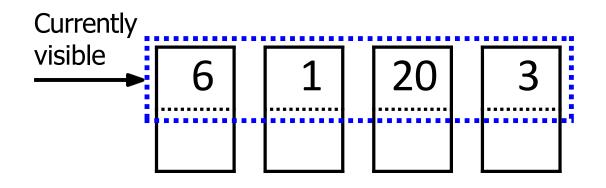
Interesting since it took quite some effort to beat 1 - 1/e for PS.

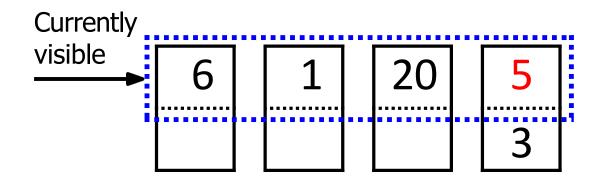
Alternative version: Max probab. of taking the maximum hidden value. Theorem. There is a stopping rule  $ALG^*$  for the two-sided game of Googol such that

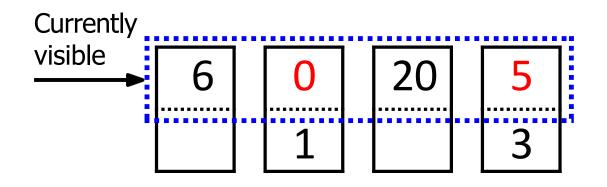
 $\mathbb{P}(ALG^* \text{ wins}) \geq 0.5001$ 

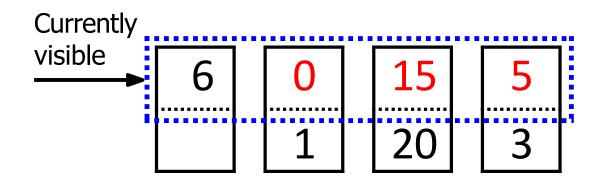
And this is almost tight

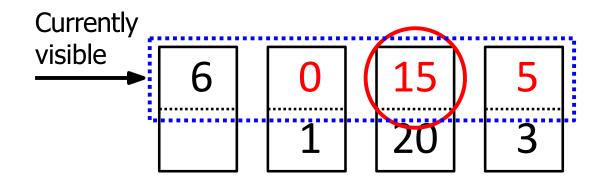
[Nuti, Vondrak SODA 2023]

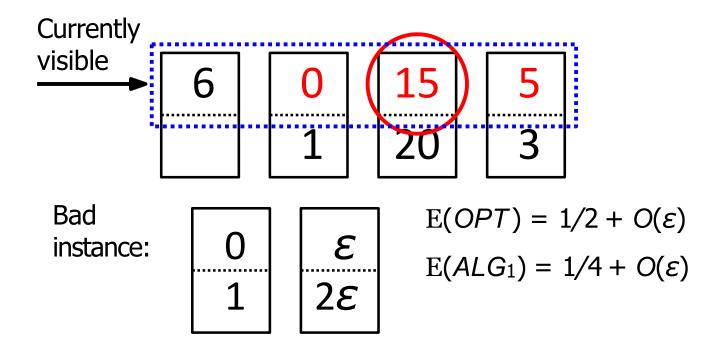


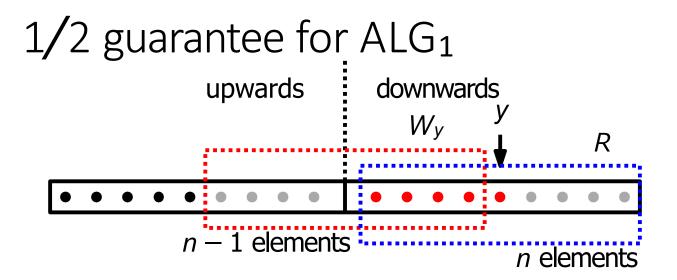








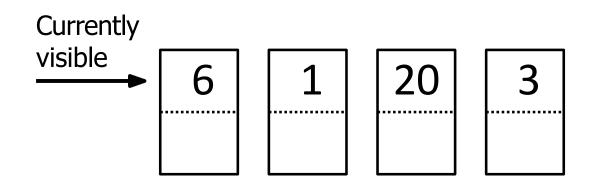


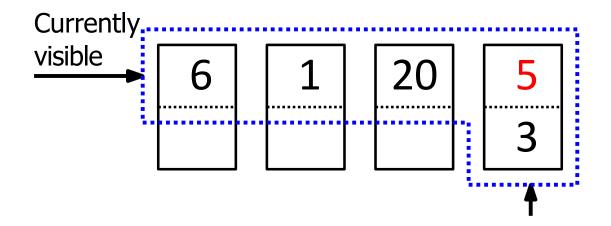


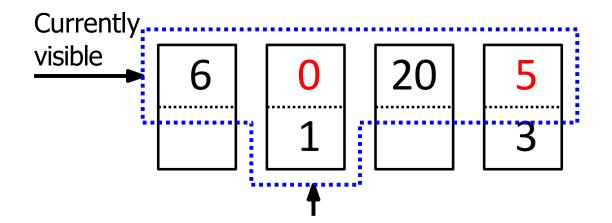
 $\mathbb{P}(OPT = y | R = S \cup \{y\}) \le 2 \cdot \mathbb{P}(ALG_1 = y | y \in R, W_y = S)$ 

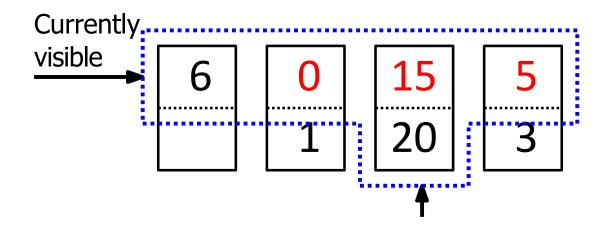
Indicator function

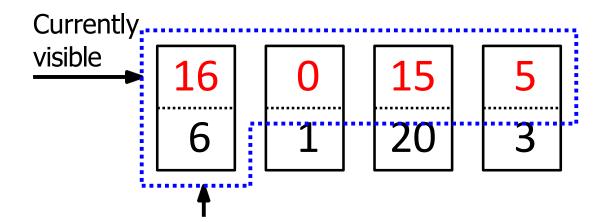
• 1 if  $y > \max S$ 0 otherwise w.p. 1/2, max S lands facing upwards (left)

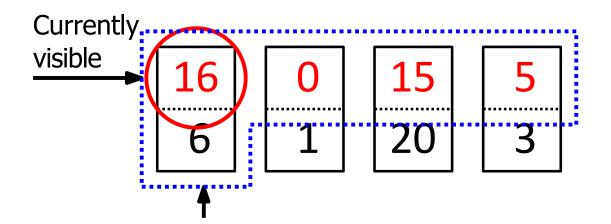






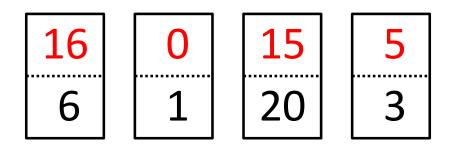






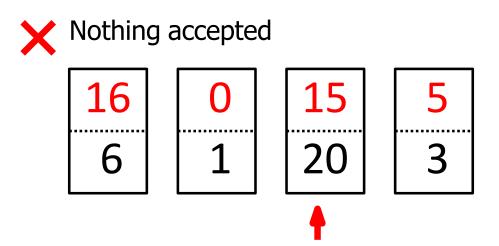
## Basic algorithm 3: Full window

Stop in first value larger than all values seen so far

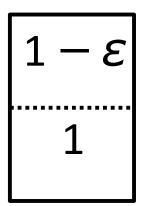


# Basic algorithm 3: Full window

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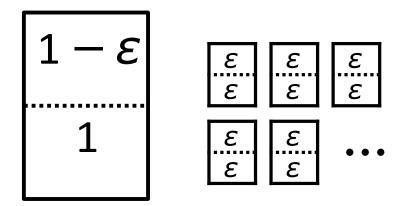
### Bad instance for ALG<sub>2</sub> and ALG<sub>3</sub>



 $E(OPT) = 1 - O(\varepsilon)$ 

If ALG sets other side of card as threshold, then  $E(ALG) \le 1/2 + O(\varepsilon)$ 

### Bad instance for ALG<sub>2</sub> and ALG<sub>3</sub>

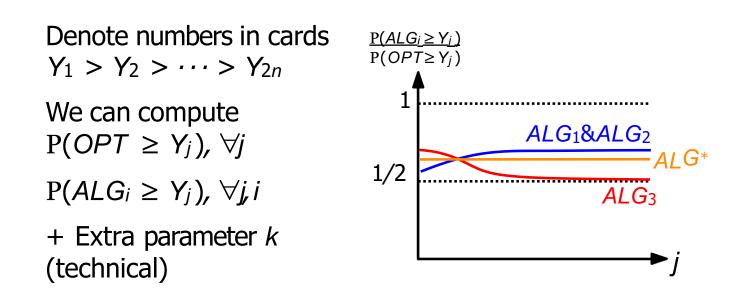


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If ALG sets other side of card as threshold, then  $E(ALG) \le 1/2 + O(\varepsilon)$ 

### Combined algorithm

•  $ALG^*$ : run  $ALG_1$  w.p.  $\alpha$ , run  $ALG_2$  w.p.  $\beta$  and run  $ALG_3$  w.p.  $1 - \alpha - \beta$  $\frac{P(ALG \ge x)}{P(OPT \ge x)} \ge c, \forall x \ge 0 \Rightarrow \frac{E(ALG)}{E(OPT)} \ge c$ 



### Two-sided googol

**Prophet-secretary.** *n* independent realizations of known distributions  $F_1, ..., F_n$  arrive sequentially in random order. Decide when to stop in order to maximize expected value.

**Data-driven version:** Distributions are unknown. Access only to one independent sample of each on beforehand.

If adversary draws numbers from distributions  $F_1, \dots, F_n$  (two of each), we obtain prophet-secretary with samples

## Two-sided googol

• Implies a factor 0.635 for prophet secretary

→ Improves upon previous  $1 - \frac{1}{e} + \frac{1}{400} \approx 0.634$  which took effort

- $\rightarrow$  Different sampling idea
- $\rightarrow$  Best known for PS is 0.669

[Azar, Chiplunkar, Kaplan EC 2018]

[Kaplan, Naori, Raz SODA 2020]

[C., Saona, Ziliotto, SODA 2019]

#### Many open questions

- $\rightarrow$  What is the best algorithm?
- $\rightarrow$  What happens in two-sided googol if we can choose the order of observation?
- $\rightarrow$ What about k-sided? Can we obtain the best possible algorithm for PS this way?

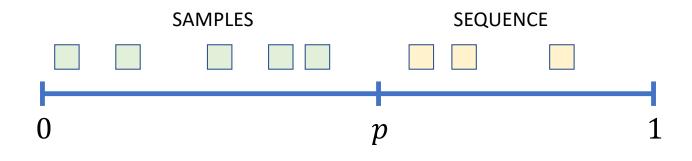
# Independent sampling model

- Set of N **unknown** values is fixed, a probability  $p \in [0,1)$  is given
- Each value is in SAMPLES with probability p, independently. Otherwise, in the SEQUENCE.
- We observe the SAMPLES and then, one by one, the values in the SEQUENCE, in uniform random order.

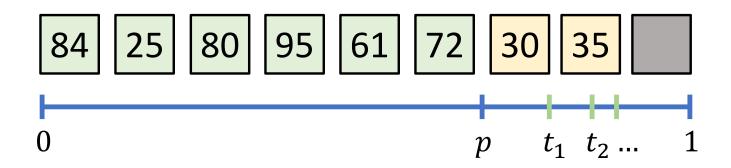


# Uniform[0,1] arrivals

- Values arrive at an independent Uniform[0,1] time
- ${\ensuremath{\, \bullet }}$  We start playing at time p



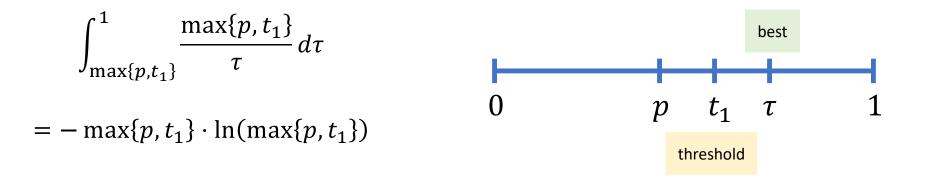
# Maximize $\mathbb{P}($ select the best)



W.I.o.g. we can look at ordinal algorithms [Moran, Snir, Manber '85] For an ordinal algorithm: the probability that a best-so-far is the best depends only in its **overall rank** and **how many elements are left**.

A **time-thresholds** algorithm achieves the best-possible guarantee.

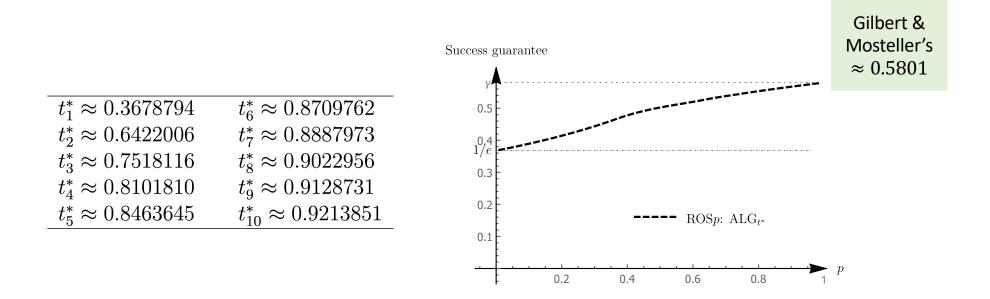
### Example: single time-threshold



Concave, maximized at  $t_1 = 1/e$  for all p

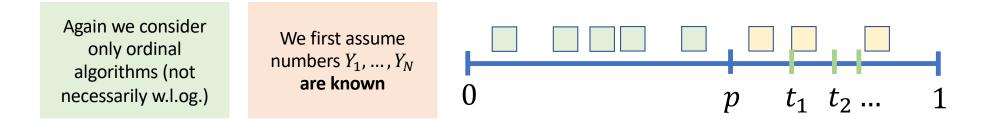
If we have a time threshold for each rank,  

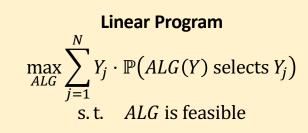
$$\sum_{i=1}^{\infty} p^{i-1} \cdot \left( 1 - \max\{p, t_i\} - \int_{\max\{p, t_i\}}^{1} \sum_{j=1}^{i} \frac{\tau - \max\{p, t_i\}}{\tau^j} d\tau \right)$$
Turns out to be separable and concave!



[C., Cristi, Feuilloley, Oosterwijk, Tsiagonias-Dimitradis SODA 2021]

# Maximize $\mathbb{E}(v_{\text{stop}})$

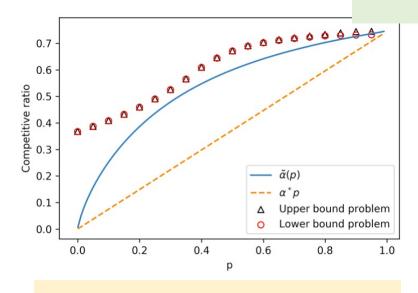




Limit Problem  

$$\sup_{\substack{t=(t_i)_{i\in\mathbb{N}}}} Y_1 - \sum_{k\geq 1} (Y_k - Y_{k+1}) (1 - F_k(t))$$
s.t.  $p \le t_i \le t_{i+1} \le 1 \quad \forall i \ge 1$   
Where  $F_k(t) = \mathbb{P}(ALG_t(Y) \ge Y_i)$ 

Best for i.i.d.  $\approx 0.745$ 



 $O\left(\frac{N}{\varepsilon}\right)$  samples are sufficient to get almost optimal guarantee of  $0.745 - \varepsilon$ Improves upon previous bound of  $O\left(\frac{N}{\varepsilon^6}\right)$ [Rubinstein, Wang, Weinberg, ITCS'20]

$$\sup_{\substack{t=(t_i)_{i\in\mathbb{N}} \\ y_1 \ge Y_2 \ge \cdots}} \frac{Y_1 - \sum_{k\ge 1} (Y_k - Y_{k+1}) (1 - F_k(t))}{\mathbb{E}(OPT(Y))}$$
  
s.t.  $p \le t_i \le t_{i+1} \le 1 \quad \forall i \ge 1$   
Where  $F_k(t) = \mathbb{P}(ALG_t(Y) \ge Y_j)$ 

$$\sup_{t=(t_i)_{i\in\mathbb{N}}} \inf_{k\geq 1} \frac{F_k(t)}{1-p^k}$$

s.t. 
$$p \le t_i \le t_{i+1} \le 1 \quad \forall i \ge 1$$

Where  $F_k(t) = \mathbb{P}(ALG_t(Y) \ge Y_j)$ 

[C., Cristi, Epstein Soto MOR 2023]

## Summary

- 1/2 PI w. one sample per distribution [Rubinstein, Wang, Weinberg ITCS 2020]
- Two-sided googol (prophet secretary with single sample)
  - 0.635 for expectation [Correa, Cristi, Epstein, Soto SODA 2020]
  - 0.5001 for probability of selecting the best [Nuti, Vondrak SODA 2023]
- Best i.i.d. PI with any number of samples [Correa, Cristi, Epstein, Soto MOR 2023]