

Online-Learning for min-max discrete problems

Beyond COmpetitive Analysis and On-line Learning (BeCOOL)

Project Leader: Evripidis Bampis

Joint work with

Dimitris Christou, Bruno Escoffier and Nguyen Kim Thang

PGMO Days 2020

December 1st, 2020

For $t = 1, 2, \dots, T$:

- 1 The player picks any feasible action $x^t \in \mathcal{X}$.
- 2 The adversary reveals any objective function $f^t \in \mathcal{F}$.
- 3 The player suffers loss $f^t(x^t)$.

Cost: $loss(\mathcal{A}) = \sum_{t=1}^T f^t(x^t)$

Benchmark: Minimize the *regret*, defined as:

$$R_T(\mathcal{A}) = |loss(\mathcal{A}) - \sum_{t=1}^T f^t(x^*)|$$

where $x^* = \arg \min_{x \in \mathcal{X}} \sum_{t=1}^T f^t(x)$.

- ① For linear objectives, any algorithm for the underlying problem translates to a vanishing-regret algorithm for its On-line Learning variant.
- ② **Question:** Can similar results be achieved for non-linear objectives?
e.g. On-line Learning MinMax Vertex cover.
Action \implies Decide a vertex cover on a static graph.
Adversary \implies Reveals the weights of the vertices.
Cost \implies The weight of the "heaviest" vertex on the cover.

What we have done:

- 1 Hardness results on the regret of any algorithm for the family of non-linear On-line Learning problems, called *MinMax problems*.
- 2 Separate the power of *FTL*-based methods and *GD*-based methods for On-line Learning in the case of non-linear objectives.
- 3 Apply the FTL method for an On-line Learning version of the *Knapsack Problem*.

Thank you!