

Energy Management Systems and Demand Response

W. van Ackooij, A. P. Chorobura,
C. Sagastizábal, H. Zidani

PGMO Days 2017

November 14, 2017

Goals

- For a toy power mix problem, to compare the pros and cons of implementing a demand-response mechanism by considering:
 - a) Load-shaving constraints
 - b) Energy-management system depending on a battery

Goals

- For a toy power mix problem, to compare the pros and cons of implementing a demand-response mechanism by considering:
 - a) Load-shaving constraints
 - b) Energy-management system depending on a battery
- Energy problems often consider cost minimization or revenue maximization. Another important concern refers to the environmental impact in terms of carbon emissions

Goals

- For a toy power mix problem, to compare the pros and cons of implementing a demand-response mechanism by considering:
 - a) Load-shaving constraints
 - b) Energy-management system depending on a battery
- Energy problems often consider cost minimization or revenue maximization. Another important concern refers to the environmental impact in terms of carbon emissions
- The inclusion of a third objective, aiming at maximizing the battery life, could also be important to take into account .

MATHEMATICAL FORMULATION

Mathematical Formulation

- N utilities K_j and T time steps
- Cost c_j of the energy generated by utility K_j
- CO₂ emission E_j from utility K_j
- g_j^t power generated by utility K_j at time t
- Technological constraints for generated power g_j^t in G_j^t (affine set)
- Customers' demand d^t at time t

$$\text{minimize} \quad \left(\sum_{j=1}^N \sum_{t=1}^T c_j g_j^t, \sum_{j=1}^N \sum_{t=1}^T E_j g_j^t \right)$$

$$\text{subject to} \quad g_j^t \in G_j^t, \quad j = 1, \dots, N, \quad t = 1, \dots, T$$
$$\sum_{j=1}^N g_j^t = d^t, \quad t = 1, \dots, T$$

Load-shaving

- The load-shaving constraint shifts in time a portion of the energy consumption (in exchange of some compensation, such as a preferential fee).

Load-shaving

- The load-shaving constraint shifts in time a portion of the energy consumption (in exchange of some compensation, such as a preferential fee).
- Shifting consumption away from the peak hours reduces generation costs and keeps the electrical network less congested.

Load-shaving

- The load-shaving constraint shifts in time a portion of the energy consumption (in exchange of some compensation, such as a preferential fee).
- Shifting consumption away from the peak hours reduces generation costs and keeps the electrical network less congested.

Model

$$\begin{aligned} -\gamma &\leq x^t \leq v^t \leq \gamma, & t = 1, \dots, T, \\ v^t &\geq 0 & t = 1, \dots, T, \\ \sum_{t=1}^T x^t &= 0, \quad \sum_{t=1}^T v^t \leq \gamma, \end{aligned}$$

- x^t is the displaced energy at time t
- v^t is the maximum power that can be displaced at each period
- γ is a bound for the power that can be shifted along the planning horizon

Energy Management System

Along the lines of

- B. Heymann, P. Martinon, F. Silva, F. Lanas, G. Jiménez, e J.F. Bonnans. *Continuous Optimal Control Approaches to Microgrid Energy Management*. <https://hal.inria.fr/hal-01129393>, 2015.

Energy Management System

Along the lines of

- B. Heymann, P. Martinon, F. Silva, F. Lanas, G. Jiménez, e J.F. Bonnans. *Continuous Optimal Control Approaches to Microgrid Energy Management*. <https://hal.inria.fr/hal-01129393>, 2015.

The battery can store energy for later use, but has a limited capacity and power.

Energy Management System

- Variables

- y^t : state of charge of the battery at time t
- P_I^t and P_O^t : input and output power of the battery at time t

- Parameters

- Q_B : maximum capacity of the battery
- $\rho_I, \rho_O \in [0, 1]$: efficiency ratios for the charge and discharge processes
- y^{min} and y^{max} : minimum and maximum of the state of charge of the battery
- P_I^{max} and P_O^{max} : maximum input and output power of the battery

Energy Management System Constraints

$$y^{t+1} - y^t = \frac{1}{Q_B} \left(P_I^t \rho_I - \frac{P_O^t}{\rho_O} \right)$$

$$\begin{cases} P_I^t \in [0, P_I^{max}] & \text{if } y^t < 0.9 \\ P_I^t \leq 100 P_I^{max} (y^t - 1)^2 & \text{otherwise} \end{cases}$$

$$P_O^t \in [0, P_O^{max}], \quad y^1 = y^T$$

$$\sum_{j=1}^N g_j^t + P_O^t - P_I^t = d^t$$

$$P_O^t = - \min \left\{ 0, \sum_{j=1}^N g_j^t - d^t \right\}$$

$$P_I^t = \max \left\{ 0, \sum_{j=1}^N g_j^t - d^t \right\}$$

for $t = 1, \dots, T$,

MULTI-OBJECTIVE OPTIMIZATION

Multi-objective problem (MOP)

$$\begin{array}{ll} \text{minimize} & f(x) = (f_1(x), \dots, f_s(x)) \\ \text{subject to} & x \in Q \end{array}$$

- $x^* \in Q$ is a **Pareto solution** if there exists no $x \in Q$ such that $f(x) \neq f(x^*)$ and

$$f_i(x) \leq f_i(x^*), \quad \text{for all } i = 1, \dots, s.$$

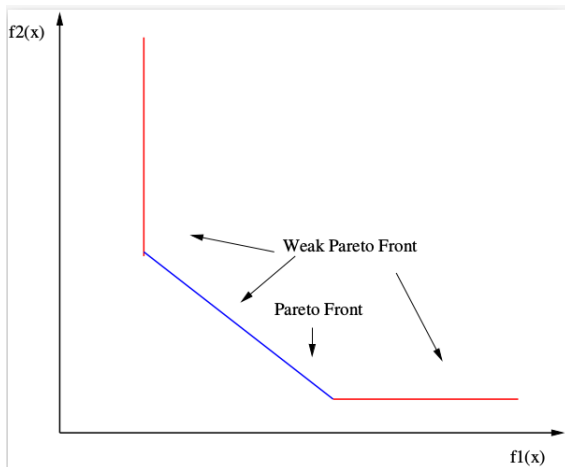
- $x^* \in Q$ is a **weak Pareto solution** if there exists no $x \in Q$ such that

$$f_i(x) < f_i(x^*), \quad \text{for all } i = 1, \dots, s.$$

- Set of Pareto and weak Pareto solutions: P and P_w
- Pareto and weak Pareto front:

$$\mathcal{F} = \{f(x) \mid x \in P\}, \quad \mathcal{F}_w = \{f(x) \mid x \in P_w\}$$

Example: Pareto and weak Pareto Front



Multi-objective programming solution method

- C.Y. Kaya and H. Maurer. *A Numerical Method for Nonconvex Multi-Objective Optimal Control Problems*. *Comput Optim Appl*, 57: 685-702, 2014.

Single objective problem P_i

$$\begin{array}{ll} \text{Minimize} & f_i(x) \\ \text{subject to:} & x \in Q \end{array}$$

- Denote x_i^* a solution of (P_i) and $f_i^* = f_i(x_i^*)$.
- Define a *utopian objective vector* β^*

$$\beta_i^* = f_i^* - \varepsilon_i$$

where $\varepsilon_i > 0$ for all $i = 1, \dots, s$.

Scalarization

Weighted Chebyshev problem (MOP_w)

$$\begin{array}{ll} \text{minimize} & \max_{i=1,\dots,s} w_i(f_i(x) - \beta_i^*) \\ \text{subject to} & x \in Q \end{array}$$

where $w_i \geq 0$, $i = 1, \dots, s$ and $\sum_{i=1}^s w_i = 1$.

Theorem [J. Jahn, Corollary 5.35]

A vector $x^* \in Q$ is a weak Pareto minimum of (MOP) if, and only if, $x^* \in Q$ is a solution of (MOP_w) for some $w_1, \dots, w_s > 0$.

Multi-objective programming solution method

Problem (MOP_w) is a non-smooth optimization problem, because of the max operator in the objective. So it is re-formulated as:

Smooth form of (MOP_w)

minimize α

subject to $\alpha \geq 0$

$x \in Q$

$w_1(f_1(x) - \beta_1^*) \leq \alpha,$

\vdots

$w_s(f_s(x) - \beta_s^*) \leq \alpha$

Algorithm by Kaya and Maurer, Comput Optim Appl, 2014

Data: $\varepsilon_1, \varepsilon_2 > 0$, $(N + 1)$ number of discretization points

$k = 1$

Compute the boundary of the Pareto front: $(f_1^*, f_2(x_1^*))$, $(f_1(x_2^*), f_2^*)$

Parameters: $\beta_i^* = f_i^* - \varepsilon_i$, $i = 1, 2$,

Initial weights: $w_0, w_f, \Delta w$

REPEAT while $k < N$

Set the current weights $w = w_0 + k\Delta w$, $w_1 = w$ and $w_2 = 1 - w$

Find a Pareto minimum x^* that solves Problem (MOP_w)

Assign a point in the Pareto front: $\bar{f}^k = (f_1(x^*), f_2(x^*))$

$k = k + 1$

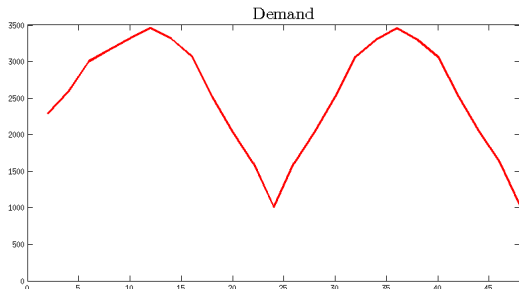
NUMERICAL RESULTS

Numerical Results

- 9 thermal power plants (3 nuclear, 2 coal, 3 gas and 1 combustion turbine)
- Solar energy g_S^t generated by the relation:

$$s^t = 75 \max \left(\sin \left(\frac{(t-4)\pi}{5} \right), 0 \right)$$

- Time horizon of 48 hours discretized in 2h time steps



Numerical Results

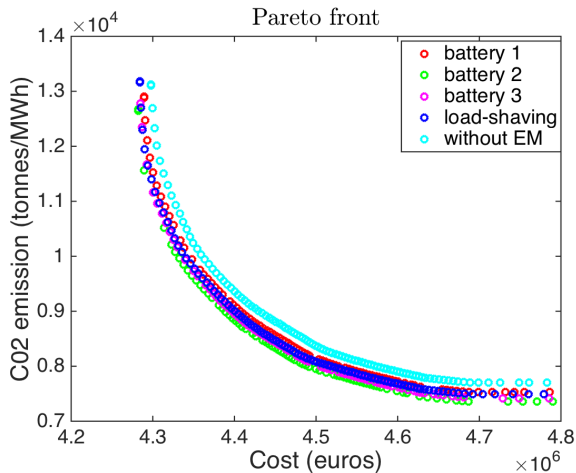
- Maximum of power that we can displaced at load-shaving

$$\gamma = 100 \text{ Megawatts.}$$

- Three instances, with different configurations for the battery:
 - **Battery one:** $Q_B = 117$, $P_I^{max} = 13.2$ and $P_O^{max} = 40$.
 - **Battery two:** $Q_B = 234$, $P_I^{max} = 26.4$ and $P_O^{max} = 80$.
 - **Battery three:** $Q_B = 200$, $P_I^{max} = 13.2$ and $P_O^{max} = 40$.

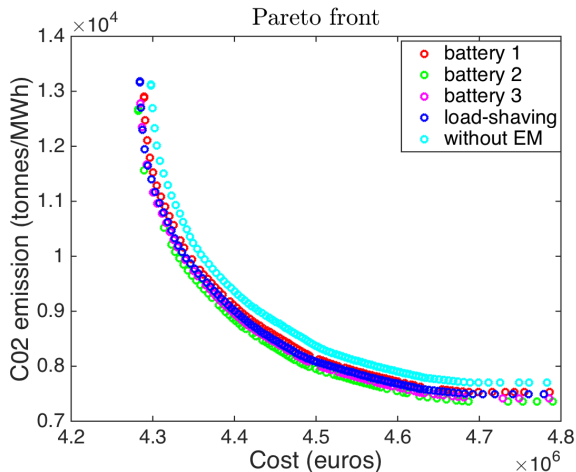
Numerical Results

Number of discretization points $N = 100$



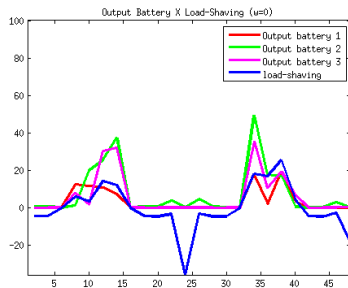
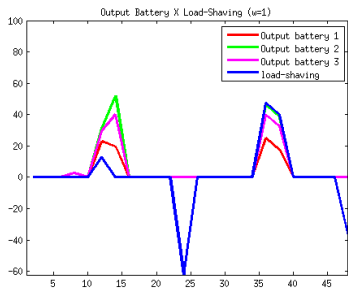
Numerical Results

Number of discretization points $N = 100$



- Best option: battery 2.

Load-shaving and Battery storage: similar behaviour



Conclusions

- Both mechanisms, load-shaving and an EMS, have a positive effect on demand response. We observe a reduction in generation cost and carbon emission.
- If the battery is sufficiently large, the results are better than load-shaving.

Future Steps

- a) In discrete time, develop a dedicated bundle method combining achievement and improvement functions, exploiting warm starts to generate the Pareto front (ongoing work).
- b) In continuous time: solve the HJB formulation (without DR, that couples all time steps) and compare with **a**).
- c) Include frequency control at peak times.

References

- [1] B. Heymann, P. Martinon, F. Silva, F. Lanas, G. Jiménez, J.F. Bonnans. Continuous Optimal Control Approaches to Microgrid Energy Management. *Energy Systems*, 2017, Online First.
- [2] R. P. Behnke, C. Benavides, F. Lanas, B. Severino, L. Reyes, J. Llanos, D. Sáez. A Microgrid Energy Management System Based on the Rolling Horizon Strategy. *IEEE Trans. on Smart Grid*, 4(2), 2013, 996-1006.
- [3] A. Chaouachi, R. M. Kamel, R. Andoulski, K. Nagasaka. Multiobjective Intelligent Energy Management for a Microgrid. *IEEE Trans. on Industrial Electronics*, 60(4), 2013, 1688-1699.
- [4] J. Jahn. *Vector Optimization: Theory, Applications, and Extensions*. Springer, Berlin (2011)
- [5] C.Y. Kaya and H. Maurer. *A Numerical Method for Nonconvex Multi-Objective Optimal Control Problems*. *Comput Optim Appl*, 57: 685-702, 2014.

Merci de votre attention