

# On the use of copulae for the joint probabilistic constrained problems

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# Problem formulation

General chance constrained optimization problem

## General chance constrained optimization problem

$$\min c(x) \quad \text{s.t.} \quad G(x) := \mathbb{P}\{g_k(x; \xi) \geq 0, k \in \mathcal{K}\} \geq p, x \in X_0 \quad (1)$$

- $x \in \mathbb{R}^n$  ... decision vector  
 $X_0 \subset \mathbb{R}^n$  ... deterministic constraints  
 $\xi \in \mathbb{R}^s$  ... random vector  
 $p$  ... fixed (high) probability  
 $\mathcal{K}$  ... index set for constraints  $g_k$

### Issues to address

- convexity of the feasible set
- computational effort.

# Problem formulation

General chance constrained optimization problem

$$\min c(x) \quad \text{s.t.} \quad G(x) = \mathbb{P}\{g_k(x; \xi) \geq 0, k \in \mathcal{K}\} \geq p, x \in X_0 \quad (1)$$

For simplicity, we assume

$$X_0 = \mathbb{R}^n \quad c(x) = c^T x \quad \mathcal{K} = \{1, \dots, K\}.$$

Very classical result

## Proposition 1

*The feasible set is convex  $\Leftrightarrow G(x)$  is quasi-concave (on  $X_0$ ).*

We will concentrate in two important special cases

- 1 nonlinear constraints with random right-hand side
- 2 linear constraints with random coefficient matrix

# Problem formulation

Constraints with random right hand side

## Constraints with random right hand side

$$\min c^T x \quad \text{s.t.} \quad G(x) = \mathbb{P}\{g_k(x) \geq \xi_k, k \in \mathcal{K}\} \geq p \quad (2)$$

i. e.

$$g_k(x; \xi) = g_k(x) - \xi_k$$

$$G(x) = \mathbb{P}\{g_k(x) \geq \xi, k \in \mathcal{K}\} \geq p,$$

Denote

$$M(p) := \{x \mid \mathbb{P}\{g_k(x) \geq \xi_k, k \in \mathcal{K}\} \geq p\}$$

... set of feasible solutions of the problem (2).

# Problem formulation

## Constraints with linear random matrix

### Constraints with linear random matrix

$$\min c^T x \quad \text{s.t.} \quad G(x) = \mathbb{P}\{\Xi x \leq h\} \geq p \quad (3)$$

i. e.

$$\begin{aligned} \xi &= (\Xi_1^T, \dots, \Xi_k^T) \\ g_k(x; \xi) &= h_k - \Xi_k x \\ G(x) &= \mathbb{P}\{\Xi_k x \leq h_k, k \in \mathcal{K}\} \geq p, \end{aligned}$$

Denote

$$X(p) := \{x \mid \mathbb{P}\{\Xi x \leq h\} \geq p\}$$

... set of feasible solutions of the problem (3).

# Outline of the talk

- 1 Introduction — problem formulation
  - finished
- 2 Dependence of constraint rows
  - overcoming row independence conditions
  - notion of copulae
- 3 Convexity of the feasible set
  - classical results (first)
  - extended result
- 4 Approximation
  - formulating the problem as a second-order cone programming (SOCP) problem

- Many practical results concerning chance-constrained programming is based on the assumption of **independence** of random rows of the problem.
- The proof are usually based on the separability property of the form

$$F(\xi) = \prod_{k \in \mathcal{K}} F_k(\xi_k)$$

where  $F$  is the distribution function of  $\xi$  and  $F_k$  its marginals.

- first approach (HOUDA (2009)): approximate the problem employing the difference

$$F(\xi) - \prod_{k \in \mathcal{K}} F_k(\xi_k)$$

- this presentation: use of **copulae** (NELSEN (2006))

# Dependence: copulae

## Definition and basic properties

### Definition 2

The **copula** is the distribution function  $C : [0; 1]^K \rightarrow [0; 1]$  of some  $K$ -dimensional random vector whose marginals are **uniformly distributed** on  $[0; 1]$ .

### Proposition 3 (Sklar's theorem)

*For any  $K$ -dimensional distribution function  $F : \mathbb{R}^K \rightarrow [0; 1]$  with marginals  $F_1, \dots, F_K$ , there exists a copula  $C$  such that*

$$\forall z \in \mathbb{R}^K \quad F(z) = C(F_1(z_1), \dots, F_K(z_K)).$$

*If, moreover,  $F_k$  are continuous, then  $C$  is uniquely given by*

$$C(u) = F(F_1^{-1}(u_1), \dots, F_K^{-1}(u_K)).$$

*Otherwise,  $C$  is uniquely determined on  $\text{range } F_1 \times \dots \times \text{range } F_K$ .*



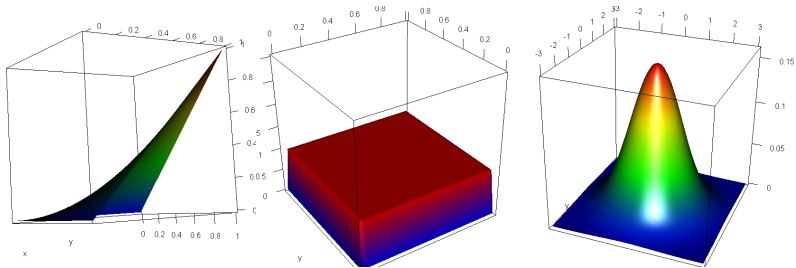
# Dependence: copulae

## Three important examples

Assume  $u = (u_1, \dots, u_K)^T \in \mathbb{R}^K$

### 1 independence (product) copula

$$\Pi(u) := \prod_{k=1}^K u_k,$$



# Dependence: copulae

Three important examples

## 3 maximum (comonotone) copula

$$M(u) := \min_k \{u_k\}$$

We also define

$$W(u) := \max \left\{ \sum_{k=1}^K u_k - K + 1, 0 \right\}$$

( $W$  fails to be a copula for  $K > 2$ )

### Proposition 4 (Fréchet-Hoeffding bounds)

For every copula  $C$  and every  $u \in \text{dom } C$

$$W(u) \leq C(u) \leq M(u)$$

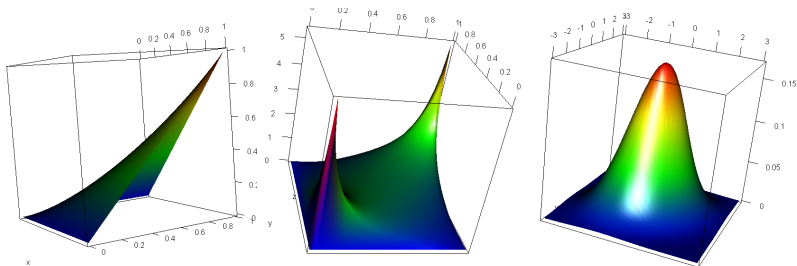
# Dependence: copulae

## Three important examples

### 3 Gaussian (normal) copula

$$C^{\Sigma}(u) := \prod_k \Phi^{\Sigma}(\Phi^{-1}(u_1), \dots, \Phi^{-1}(u_K))$$

where  $\Phi^{\Sigma}$  is the distribution function of multivariate normal distribution with zero mean, unit variance and correlation matrix  $\Sigma$



# Dependence: copulae

## Archimedean copulae

### Definition 5

A copula  $C$  is called **Archimedean** if there exists a continuous strictly decreasing function  $\psi : [0; 1] \rightarrow \mathbb{R}_+$ , called **generator of  $C$** , such that  $\psi(1) = 0$  and

$$C(u) = \psi^{-1} \left( \sum_{i=1}^n \psi(u_i) \right). \quad (4)$$

If  $\lim_{u \rightarrow 0} \psi(u) = +\infty$  then  $C$  is called a **strict Archimedean copula** and  $\psi$  is called a **strict generator**.

### Properties of copula generator

- $\psi$  is **convex**
- $\psi^{-1}$  is continuous strictly decreasing convex on  $[0; \psi(0)]$

# Dependence: copulae

Archimedean copulae: copula generators

## Proposition 6

Let  $\psi : [0; 1] \rightarrow \mathbb{R}^+$  be convex, strictly decreasing function with  $\psi(1) = 0$ ,  $\lim_{u \rightarrow 0} \psi(u) = +\infty$ , and

$$(-1)^k \frac{d^k}{dt^k} \psi^{-1}(t) \geq 0 \quad \forall k = 0, 1, \dots, K \text{ and } \forall t \in \mathbb{R}^+.$$

Then  $\psi$  is a strict copula generator.

## Proposition 7

Let  $\psi : [0; 1] \rightarrow \mathbb{R}^+$  be convex, strictly decreasing function with  $\psi(1) = 0$ ,  $\lim_{u \rightarrow 0} \psi(u) = +\infty$ . Then  $\psi$  is a strict copula generator for every  $K \geq 2$  iff

$$(-1)^k \frac{d^k}{dt^k} \psi^{-1}(t) \geq 0 \quad \forall k = 0, 1, \dots, \text{ and } \forall t \in \mathbb{R}^+.$$

Such function  $\psi^{-1}$  is called **completely monotonic**.

# Dependence: copulae

## Archimedean copulae: copula generators

Practical advantages of Archimedean copulae:

- associative class (separability)
- explicit formulae of generators for most common copulae
- model dependence through one “nice” generator function and usually one or a small number of parameters
- many families adapted to a concrete problem setting  
(NELSEN (2006) provides a table of 22 one-parameter families of Archimedean copulae)

Some known shortcomings:

- Gaussian copula is **not** Archimedean
- all copula margins are the same  $\Rightarrow$  only symmetric dependence structures described
- limited area of dependence structures (due to small number of parameters)
- less ability to capture negative dependence

# Dependence: copulae

## Examples of Archimedean copulae

- 1 independence (product) copula

$$\psi(t) := -\ln t,$$

- 2 Gumbel-Hougaard copulae, with  $\theta \geq 1$

$$\psi_{\theta}(u) := (-\ln t)^{\theta}$$

Limiting cases

$$C_1 = \Pi$$

$$C_{+\infty} = M$$

[see animation]

- 3 Clayton copulae, with  $\theta \geq 0$

$$\psi_{\theta}(u) := -\frac{1}{\theta}(t^{-\theta} - 1)$$

Limiting cases

$$C_0 = \Pi$$

$$C_{+\infty} = M$$

[see animation]

# Dependence: copulae

Formulation of chance-constrained problem with random RHS

$$\min c^T x \quad \text{s.t.} \quad G(x) = \mathbb{P}\{g_k(x) \geq \xi_k, k \in \mathcal{K}\} \geq p \quad (2)$$

## Theorem 8

*If the joint distribution of  $\xi$  is driven by an Archimedean copula with the generator  $\psi$  then the feasible set of chance-constrained problem (2) can be equivalently written as*

$$M(p) = \left\{ x \in X \mid \exists y_k \geq 0, \sum_{k=1}^K y_k = 1 : \right. \\ \left. \psi[F_k(g_k(x))] \leq \psi(p)y_k \text{ for every } k \in \mathcal{K} \right\}. \quad (5)$$

*where  $F_k$  are one-dimensional distribution functions of components  $\xi_k$  of  $\xi$ .*



# Normal distribution

Normal distribution with independent constraint rows

$$\min c^T x \quad \text{s.t.} \quad G(x) = \mathbb{P}\{\Xi x \leq h\} \geq p \quad (3)$$

- If the rows  $\Xi_k^T$  are independent and follow  $N_n(\mu_k; \Sigma_k \succ 0)$  then

$$\xi_k(x) := \frac{\Xi_k^T x - \mu_k^T x}{\sqrt{x^T \Sigma_k x}}, \quad g_k(x) := \frac{h_k - \mu_k^T x}{\sqrt{x^T \Sigma_k x}},$$

so

$$G(x) = \mathbb{P}\{g_k(x) \geq \xi_k(x), \quad k \in \mathcal{K}\}$$

where  $\xi_k(x) \sim N(0; 1)$ .

- If  $K = 1$  (only one constraint) then

$$X(p) = \left\{ x \in X \mid \mu_1^T x + \Phi^{-1}(p) \sqrt{x^T \Sigma_1 x} \leq h_1 \right\}.$$

- To extend the result to  $K > 1$  (more constraint rows): introduce auxiliary variables  $y_k$ . If the rows are **independent**, then (Cheng, Lasser(2012))

$$X(p) = \left\{ x \in X \mid \exists y_k \geq 0, \sum_{k=1}^K y_k = 1 : \right.$$

$$\left. \mu_k^T x + \Phi^{-1}(p^{y_k}) \sqrt{x^T \Sigma_k x} \leq h_k \text{ for every } k \in \mathcal{K} \right\}.$$

# Normal distribution and dependence

Chance-constrained problem with dependent constraint rows

$$\min c^T x \quad \text{s.t.} \quad G(x) = \mathbb{P}\{\Xi x \leq h\} \geq p \quad (3)$$

## Theorem 9

Suppose  $\Xi_k^T \sim N(\mu_k, \Sigma_k \succ 0)$ . Then the feasible set of (3) is

$$X(p) = \left\{ x \in X \mid \exists y_k \geq 0, \sum_{k=1}^K y_k = 1 : \right. \\ \left. \mu_k^T x + \Phi^{-1}(\psi^{-1}(y_k \psi(p))) \sqrt{x^T \Sigma_k x} \leq h_k, k \in \mathcal{K} \right\}$$

where

- 1  $\Phi$  is one-dimensional standard normal distribution function, and
- 2  $\psi$  is a generator of an Archimedean copula describing the dependence properties of the rows of the matrix  $\Xi$ .

# Convexity of the feasible set

Generalized concavity properties:  $r$ -concave functions

## Definition 10

$f(\cdot)$  is  $r$ -concave iif for any  $x, y$  such that  $f(x) > 0, f(y) > 0$  and  $\lambda \in [0; 1]$  we have

$$f(\lambda x + (1 - \lambda)y) \geq [\lambda f^r(x) + (1 - \lambda)f^r(y)]^{1/r}$$

cases  $r = -\infty, 0, +\infty$  treated by continuity.

$r = -\infty$	$RHS = \min\{f(x), f(y)\}$	$\dots f$ quasi-concave
$r < 0$		$\dots f^r$ convex
$r = 0$	$RHS = f^\lambda(x)f^{1-\lambda}(y)$	$\dots f$ log-concave (log $f$ concave)
$r > 0$		$\dots f^r$ concave
$r = 1$		$\dots f$ concave
$r = +\infty$	$RHS = \max\{f(x), f(y)\}$	$\dots f$ quasi-convex

If  $f$  is  $r^*$ -concave, it is also  $r$ -concave for all  $r \leq r^*$

$\Rightarrow$  every  $r$ -concave function is quasi-concave.

PRÉKOPA (1971) (log-concave measures)

# Convexity of the feasible set

Generalized concavity properties:  $r$ -concave probability distributions

## Definition 11

Probability measure  $\mathbb{P}$  (on  $\mathcal{B}(\mathbb{R}^s)$ ) is  $r$ -concave iff for any Borel convex subset  $A, B$  such that  $\mathbb{P}(A) > 0, \mathbb{P}(B) > 0$  and  $\lambda \in [0; 1]$  we have

$$\mathbb{P}(\lambda A + (1 - \lambda)B) \geq [\lambda \mathbb{P}^r(A) + (1 - \lambda) \mathbb{P}^r(B)]^{1/r}$$

cases  $r = -\infty, 0, +\infty$  treated by continuity.

Properties:

- 1  $r$ -concave probability measure has  $r$ -concave distribution function
- 2 quasi-concave measure  $\mathbb{P}$  on  $\mathbb{R}^s$  with  $\dim \text{supp } \mathbb{P} = s$  has a density
- 3  $r$ -concave density  $\Leftrightarrow \frac{r}{1+mr}$ -concave measure on convex subset  $\Omega \subset \mathbb{R}^s$  of  $\dim m > 0$  (so for  $r > -\frac{1}{m}$ )

BORELL (1975), BRASCAMP, LIEB (1976)

# Convexity of the feasible set

Classical result

## Theorem 12

If

- 1  $g_k(\cdot, \cdot), k \in \mathcal{K} \dots$  quasi-concave jointly in both arguments
- 2  $\xi \in \mathbb{R}^s \dots$  random variable with  $r$ -concave probability distribution

then the feasible set

$$X_p := \{x \mid G(x) \geq p\}$$

is convex and closed.

- consequence of a general theorem by PRÉKOPA (1971), see also PRÉKOPA (1995) SHAPIRO, RUSZCZYŃSKI, DENTCHEVA (2009))
- in fact, (ii) means quasi-concave probability distribution (or  $-\frac{1}{s}$ -concave density);
- many prominent multivariate distributions has log-concave (or at least quasi-concave and/or for some parameters) distribution so that (ii) is not tie (uniform, normal, Wishart, Beta, Dirichlet, Gamma, Cauchy, Pareto)

# Convexity of the feasible set

Constraints with random right hand side

$$\min c^T x \quad \text{s.t.} \quad G(x) = \mathbb{P}\{g_k(x) \geq \xi_k, k \in \mathcal{K}\} \geq p \quad (2)$$

Recall  $g_k(x; \xi) = g_k(x) - \xi_k$

- $g_k(x; \xi)$  required quasi-concave in both arguments
- Issue: quasi-concavity **not preserved** under additions
- **Classical result:** if  $g_k(\cdot)$  concave  $\Rightarrow g_k(\cdot; \cdot)$  concave  $\Rightarrow$  assumption (i) of Theorem 12 fulfilled.

Idea: HENRION, STRUGAREK (2008)

- relax concavity requirement on  $g_k(\cdot)$
- strengthen quasi-concavity requirement on distribution of  $\xi$

# Convexity of the feasible set

$r$ -decreasing density

Definition 13 (HENRION, STRUGAREK (2008))

$f_\xi(\cdot)$  is an  $r$ -decreasing density of one-dimensional random variable  $\xi$  if

- 1  $f_\xi$  is continuous on  $(0; +\infty)$
- 2  $t^r f_\xi(t)$  is (strictly) decreasing for all  $t > t^*$  and some threshold  $t^* > 0$

- $r = 0$  ... density decreasing in classical sense
- $f_\xi$   $r^*$ -decreasing for some  $r^* \Rightarrow r$ -decreasing for all  $r \geq r^*$

Lemma 14

*The normal distribution has  $r$ -decreasing density for every  $r > 0$  with threshold  $t^* = \frac{1}{2} \left( \mu + \sqrt{\mu^2 + 4r\sigma^2} \right)$*

- for standard normal distribution:  $t^* = \sqrt{r}$

# Convexity of the feasible set

Constraints with random right hand side

$$\min c^T x \quad \text{s.t.} \quad G(x) = \mathbb{P}\{g_k(x) \geq \xi_k, k \in \mathcal{K}\} \geq p \quad (2)$$

Proposition 15 (HENRION, STRUGAREK (2008))

If

- 1  $g_k(\cdot)$  are  $(-r_k)$ -concave with  $r_k > 0$
- 2  $\xi_k$  are independent with  $(r_k + 1)$ -decreasing densities with thresholds  $t_k^* > 0$
- 3  $p > \max\{F_k(t_k^*)\}$

Then the feasible set  $M(p)$  of (2) is convex.

- Henrion and Strugarek(2011) generalized the result for dependency given by so-called *log-exp-concave* copulae
- our result similar, but based on properties of Archimedean copulae



# Convexity of the feasible set

Constraints with random right hand side

$$\min c^T x \quad \text{s.t.} \quad G(x) = \mathbb{P}\{g_k(x) \geq \xi_k, k \in \mathcal{K}\} \geq p \quad (2)$$

## Theorem 16

*If*

- 1  $g_k(\cdot)$  are  $(-r_k)$ -concave with  $r_k > 0$
- 2 the marginal distributions functions  $F_k$  have  $(r_k + 1)$ -decreasing densities with thresholds  $t_k^*$
- 3 the joint distribution of  $\xi$  is driven by an Archimedean copula with a strict generator  $\psi$  such that  $\psi^{-1}$  is completely monotonic;
- 4  $p > \max\{F_k(t_k^*)\}$

*Then the feasible set  $M(p)$  of (2) is convex.*

- independent, Gumbel-Hougaard, Clayton (and many other) copulae satisfy assumption (iii) of Theorem 16

# Convexity of the feasible set: main result

Chance-constrained problem with dependent constraint rows

$$\min c^T x \quad \text{s.t.} \quad G(x) = \mathbb{P}\{\Xi x \leq h\} \geq p \quad (3)$$

## Theorem 17

If

- 1 the rows  $\Xi_k^T \sim N(\mu_k, \Sigma_k \succ 0)$ ;
- 2 the joint distribution function of standardized rows is driven by an Archimedean copula with a generator  $\psi$

then the problem (3) can be equivalently written as

$$\min c^T x \quad \text{s.t.} \quad \mu_k^T x + \Phi^{-1}(\psi^{-1}(y_k \psi(p))) \sqrt{x^T \Sigma_k x} \leq h_k, \\ \sum_k y_k = 1, y_k \geq 0, k \in \mathcal{K}.$$

Moreover, if

- 3  $\psi^{-1}$  is completely monotonic;
- 4  $p > p^* := \Phi\left(\max\{\sqrt{3}, 4\lambda_{\max}^{(k)}[\lambda_{\min}^{(k)}]^{-3/2}\|\mu_k\|\}\right)$ , where  $\lambda_{\max}^{(k)}, \lambda_{\min}^{(k)}$  are largest and lowest eigenvalues of the matrices  $\Sigma_k$ ,

then the problem is convex.

# Approximation to SOCP problems: insights

Lower and outer approximation

## Lemma 18

The function  $y \mapsto \Phi^{-1}(\psi^{-1}(y_k \psi(p)))$  is convex.

Consequence: linear approximation results in

- 1 piecewise tangent approximation ( $\Rightarrow$  outer bound for feasible solutions)
- 2 piecewise linear approximation ( $\Rightarrow$  inner bound for feasible solutions)

Hence we obtain two SOCP problems of the form

$$\begin{aligned} \min c^T x \quad \text{s.t.} \quad & \mu_k^T x + \sqrt{z^k{}^T \Sigma_k z^k} \leq h_k, \\ & z^k \geq a_{kj} x + b_{kj} w^k, \quad k \in \mathcal{K}, j \in \mathcal{J} \\ & \sum_k w^k = x, \quad w^k \geq 0, z^k \geq 0, \quad k \in \mathcal{K}. \end{aligned}$$

$\mathcal{J}$  is the index set of partition points of  $[0; 1]$ ,  $a_{kj}$  and  $b_{kj}$  are given by the linear approximation above.

Details not presented here (technique described in Cheng, Lisser(2012)).





## In this presentation

- Equivalent deterministic formulation of the linear chance-constrained problems with random matrix of **dependent** rows was given.
- Row dependence modeled through Archimedean copulae.
- Convexity of the feasible set proven for sufficiently high probabilities.
- Inner and outer approximation of the feasible set formulated as SOCP problems.

## Under actual investigation

- possible extensions over normal distribution
- checking different class of Archimedean copulae for the convexity
- copula estimation
- numerical tests (comparison with other numerical methods)
- application in power industry

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